

Delay of systems in cascade

(4)

Delay of a circuit can be defined ~~as~~ using moments of the impulse response

$$T_D = \frac{\int_{-\infty}^{+\infty} t h(t) dt}{\int_{-\infty}^{+\infty} h(t) dt}$$

i.e. the time taken for
the impulse to reach its
center of mass.

Elmore delay

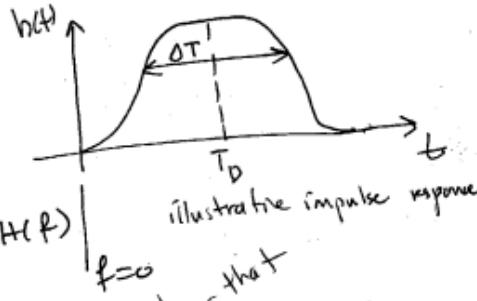
But in the frequency domain it corresponds to

$$\int_{-\infty}^{+\infty} t h(t) dt = - \frac{1}{j2\pi} \left. \frac{d}{df} H(f) \right|_{f=0}$$

$$\int_{-\infty}^{+\infty} h(t) dt = H(0)$$

⇒

$$T_D = \frac{-1}{j2\pi H(0)} \left. \frac{d}{df} H(f) \right|_{f=0}$$



Using this definition it is easy to show that the Elmore delay of a single-pole low-pass system to be $\frac{1}{2\pi f_0}$

comprise $H(f)$ is not the Fourier transform, but it is a function of not $w=2\pi f$, and actually $H(f) = H(j2\pi f)$

$\xrightarrow{\text{Frequency response}}$ $\xrightarrow{\text{Fourier transform}}$

$$\int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt = \frac{1}{2\pi} \text{FI}(w) = H(f)$$

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$$\frac{d}{dw} \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt = -j \int f(t) e^{-j\omega t} dt = \frac{d \text{FI}(w)}{dw} = \frac{1}{2\pi} \frac{d}{df} H(f) = \frac{1}{2\pi}$$

$$\int_{-\infty}^{\infty} t f(t) dt = \left[\int_{-\infty}^{\infty} t f(t) e^{-j\omega t} dt \right]_{w=0} = \frac{1}{-j} \frac{d}{dw} \text{FI}(w) \Big|_{w=0}$$

$$w = 2\pi f$$

$$\frac{d w}{d f} = 2\pi$$

$$\frac{d}{df} H(f) = \frac{dw}{df} \frac{d}{dw} \text{FI}(w)$$

$$= 2\pi \frac{d \text{FI}(w)}{dw}$$

$$\frac{d}{dw} \int_{-\infty}^{\infty} t^2 f(t) e^{-j\omega t} dt = \frac{1}{-j} \frac{d^2}{dw^2} \text{FI}(w)$$

$$\frac{d}{dt} \text{FI}(w) =$$

$$= \frac{dw}{df} \frac{d \text{FI}(w)}{dw}$$

$$(-j)^2 \int_{-\infty}^{\infty} t^2 f(t) e^{-j\omega t} dt = \frac{d^2}{dw^2} \text{FI}(w)$$

$$\int_{-\infty}^{\infty} t^2 f(t) dt = \left[\int_{-\infty}^{\infty} t^2 f(t) e^{-j\omega t} dt \right]_{w=0} = - \frac{d^2}{dw^2} \text{FI}(w) \Big|_{w=0} = - \frac{d^2}{dw^2} \text{FI}(0)$$

$$\int_{-\infty}^{\infty} t f(t) dt = \frac{1}{-j} \frac{d}{dw} \text{FI}(w) \Big|_{w=0}$$

$$T_D = \frac{\int_{-\infty}^{\infty} t f(t) dt}{\int_{-\infty}^{\infty} f(t) dt} = \frac{\text{FI}(0)}{H(0)}$$

\Leftarrow 1 more delay

(2)

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If we have 2 systems in cascade
 with $h_1(t)$ & $h_2(t)$ and corresponding fourier
 transforms

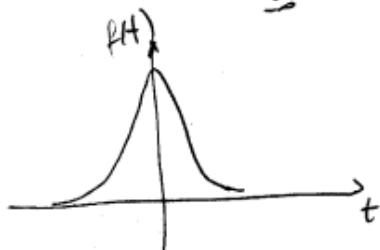
$$\begin{aligned}
 T_{D,\text{total}} &\equiv \frac{1}{-j H_1(0) H_2(0)} \left. \frac{d}{dw} [H_1(w) H_2(w)] \right|_{w=0} \\
 &= \frac{1}{-j H_1(0) H_2(0)} \left. \left[H_1(w) \frac{d}{dw} H_2(w) + H_2(w) \frac{d}{dw} H_1(w) \right] \right|_{w=0} \\
 &= \frac{\left. \frac{d}{dw} H_2(w) \right|_{w=0}}{-j H_2(0)} + \frac{\left. \frac{d}{dw} H_1(w) \right|_{w=0}}{-j H_1(0)} = T_{D1} + T_{D2}
 \end{aligned}$$

rise time.

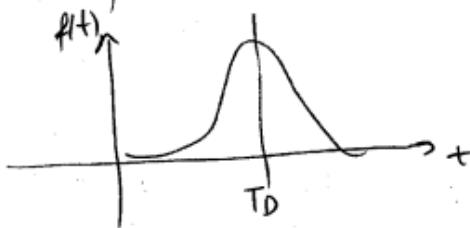
The risetime of an impulse response centered around $t=0$ can be defined as

$$\left(\frac{\Delta t}{2}\right)^2 = \frac{\int_{-\infty}^{+\infty} t^2 f(t) dt}{\int_{-\infty}^{+\infty} f(t) dt}$$

which is a measure of the spread i.e. radius of gyration



where $T_D = 0$



if $T_D \neq 0$

it should be moved to T_D by

$$\left(\frac{\Delta t}{2}\right)^2 = \frac{\int_{-\infty}^{+\infty} (t-T_D)^2 f(t) dt}{\int_{-\infty}^{+\infty} f(t) dt} = \frac{\int_{-\infty}^{+\infty} t^2 f(t) dt - T_D^2 \int_{-\infty}^{+\infty} f(t) dt}{\int_{-\infty}^{+\infty} f(t) dt}$$

(1)

$$\int_{f=0}^{+\infty} t^2 h(t) = -\frac{1}{(2\pi)^2} \left. \frac{d^2}{dt^2} H(f) \right|_{f=0}$$

$$\frac{(\Delta T)^2}{4} = \frac{\int_{-\infty}^{+\infty} t^2 h(t) dt}{\int h(t) dt} - T_D^2 = \frac{\int_{-\infty}^{+\infty} t^2 h(t) dt}{\int h(t) dt} - \left[\frac{\int_{-\infty}^{+\infty} t h(t) dt}{\int h(t) dt} \right]^2$$

$$\frac{(\Delta T)^2}{4} = -\frac{\frac{1}{(2\pi)^2} \bar{H}}{H} - \left[\frac{1}{(2\pi)^2} \frac{\bar{H}^2}{H} \right]^2 = -\frac{\frac{1}{(2\pi)^2} \bar{H}}{H} - \left[\frac{1}{(2\pi)^2} \frac{\bar{H}^2}{H^2} \right]$$

(formula)
sign error at the back

$$\frac{\Delta T^2}{4} = -\frac{\bar{H} \bar{H} + \bar{H}^2}{H^2 (2\pi)^2} \rightarrow \boxed{\pi^2 \Delta T^2 = \frac{-\bar{H} \bar{H} + \bar{H}^2}{H^2}}$$

$$\pi^2 \Delta T^2 = \frac{-H_1 \bar{H}_1 H_2 + 2 \bar{H}_1 \bar{H}_2 + H_1 \bar{H}_2}{H^2} + \frac{H_1 H_2 + H_1 \bar{H}_2}{H^2}$$

$$\begin{aligned} \pi^2 \Delta T^2 &= \frac{-H_1 H_2 \bar{H}_1 H_2 + 2 H_1 H_2 \bar{H}_1 \bar{H}_2 + \bar{H}_1 \bar{H}_2 H_1 \bar{H}_2 + \bar{H}_1 \bar{H}_2^2 + 2 H_1 \bar{H}_1 H_2 \bar{H}_2 + H_1^2 \bar{H}_2^2}{H^2} \\ &= \frac{-H_1 \bar{H}_1 H_2^2 + 2 H_1 H_2 \cancel{\bar{H}_1 \bar{H}_2} + \cancel{\bar{H}_1 \bar{H}_2 H_1 \bar{H}_2} + \cancel{\bar{H}_1 \bar{H}_2^2} + 2 H_1 \bar{H}_1 H_2 \bar{H}_2 + H_1^2 \bar{H}_2^2}{H_1^2 H_2^2} \\ &= \frac{-H_1 \bar{H}_1}{H_1^2} + \frac{\bar{H}_1^2}{H_1^2} + \frac{-H_2 \bar{H}_2 + \bar{H}_2^2}{H_2^2} = \pi^2 \Delta T_1^2 + \pi^2 \Delta T_2^2 \end{aligned}$$

$$\Rightarrow \Delta T^2 = \Delta T_1^2 + \Delta T_2^2$$

$$H = H_1 H_2$$

$$\frac{d}{dt} H = \frac{d}{dt} H_1 H_2 = \dot{H}_1 H_2 + H_1 \dot{H}_2$$

$$\frac{d}{dt} \frac{d}{dt} H = \frac{d}{dt} \frac{d}{dt} H_1 H_2 = \frac{d}{dt} (\ddot{H}_1 H_2 + H_1 \ddot{H}_2)$$

$$\frac{d^2}{dt^2} H_1 H_2 = \ddot{H}_1 H_2 + \dot{H}_1 \dot{H}_2 + \ddot{H}_1 \dot{H}_2 + H_1 \ddot{H}_2$$

$$\pi^2 \Delta T_1^2 = \frac{-\ddot{H}_1 H_1 + \dot{H}_1^2}{H_1^2} \quad \pi^2 \Delta T_2^2 = \frac{-\ddot{H}_2 H_2 + \dot{H}_2^2}{H_2^2}$$

LINEAR PHASE CIRCUIT

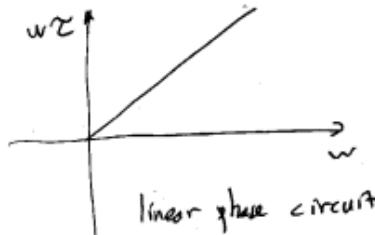
$$EE(\omega) = \int_{-\infty}^{+\infty} h(t) e^{-j\omega t} dt$$

$$h(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} EE(\omega) e^{j\omega t} d\omega$$

$$h(t-\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} EE(\omega) e^{j\omega(t-\tau)} d\omega$$

$$h(t-\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} EE(\omega) e^{j\omega t} \cdot e^{-j\omega\tau} d\omega$$

$$h(t-\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} EE(\omega) e^{-j\omega\tau} e^{j\omega t} d\omega$$



* weighted average of $(t - T_D)^2$

$$\left(\frac{\Delta T}{2}\right)^2 = \frac{\int_{-\infty}^{+\infty} (t - T_D)^2 h(t) dt}{\int_{-\infty}^{+\infty} h(t) dt}$$

total mass = $\int h(t) dt$
 the tighter the distance \Rightarrow
 the shorter is the rise time

$$= \frac{\int t^2 h(t) dt}{\int h(t) dt} - 2T_D \frac{\int t h(t) dt}{\int h(t) dt} + T_D^2 \frac{\int h(t) dt}{\int h(t) dt}$$

$$\left(\frac{\Delta T}{2}\right)^2 = \frac{\int t^2 h(t) dt}{\int h(t) dt} - 2T_D^2 + T_D^2 = \frac{\int h(t) dt}{\int h(t) dt}$$

Example

