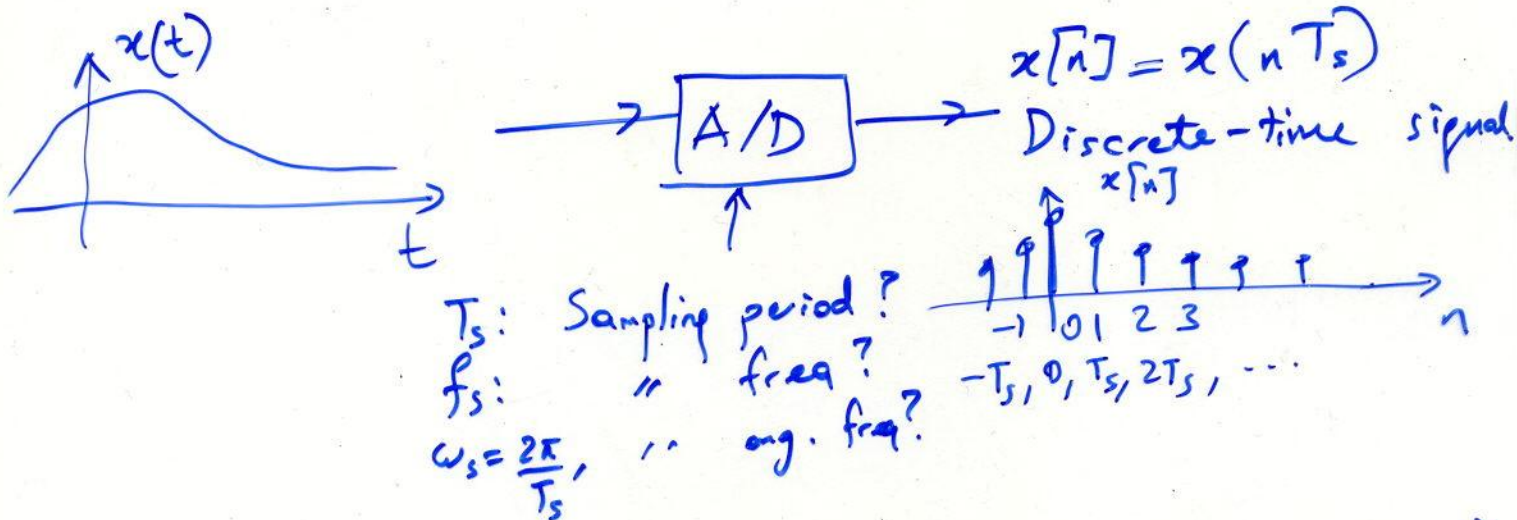


Sampling Theorem

Let $x(t)$ be a C.T. signal.



Shannon's Sampling Theorem (Kolmogorov, Whitaker)

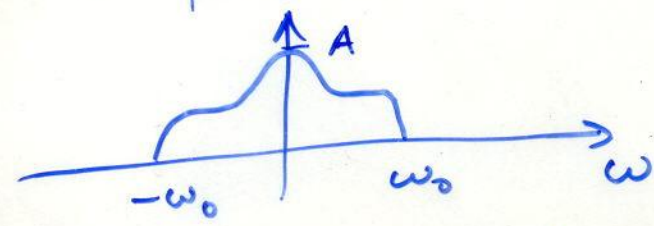
Let $x(t)$ be a band-limited signal, i.e.,

$X(j\omega) = 0$ for $|\omega| > \omega_0$. Sample $x(t)$

and obtain the discrete-time signal $x[n]$:
 $x[n] = x(nT_s)$, $n = 0, \pm 1, \pm 2, \dots$. Given

the samples, $x(t)$ can be perfectly reconstructed
 if $\omega_s > 2\omega_0$. (sampling freq. $> 2 \times$
 BW) i.e., $f_s > 2f_0$ or $\frac{2\pi}{T_s} > 2\omega_0$

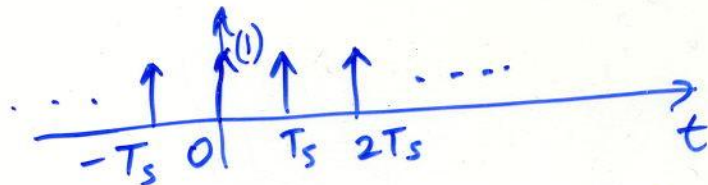
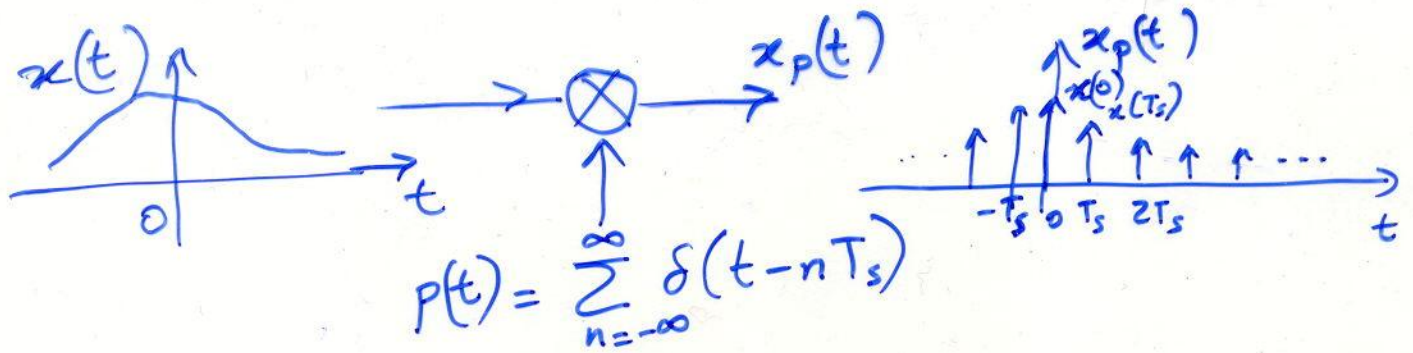
* $x(t)$ is bandlimited:



($\omega_s > 2\omega_0$
Nyquist freq.)

- * Telephone speech : $f_s = 8 \text{ kHz}$ ($f_0 = 4 \text{ kHz}$)
- * Music CD : $f_s = 44 \text{ kHz}$

Proof:



$$x_p(t) = \sum_{n=-\infty}^{\infty} x(nT_s) \delta(t - nT_s) = x(t) \cdot p(t).$$

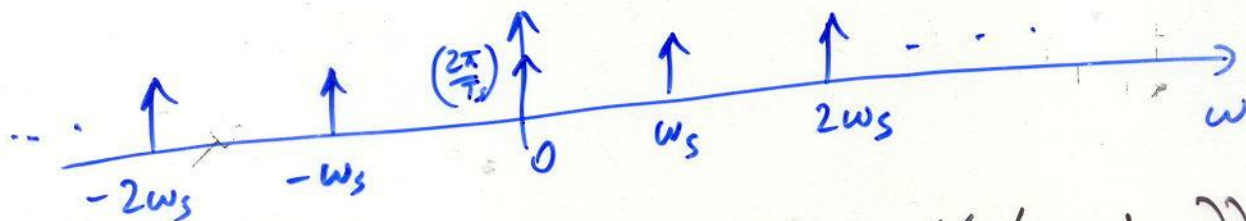
$\equiv x[n] = x(nT_s)$ discrete-time signal
 \equiv samples of the cont. time signal.

In Fourier Domain

$$X_p(j\omega) = \frac{1}{2\pi} X(j\omega) * P(j\omega)$$

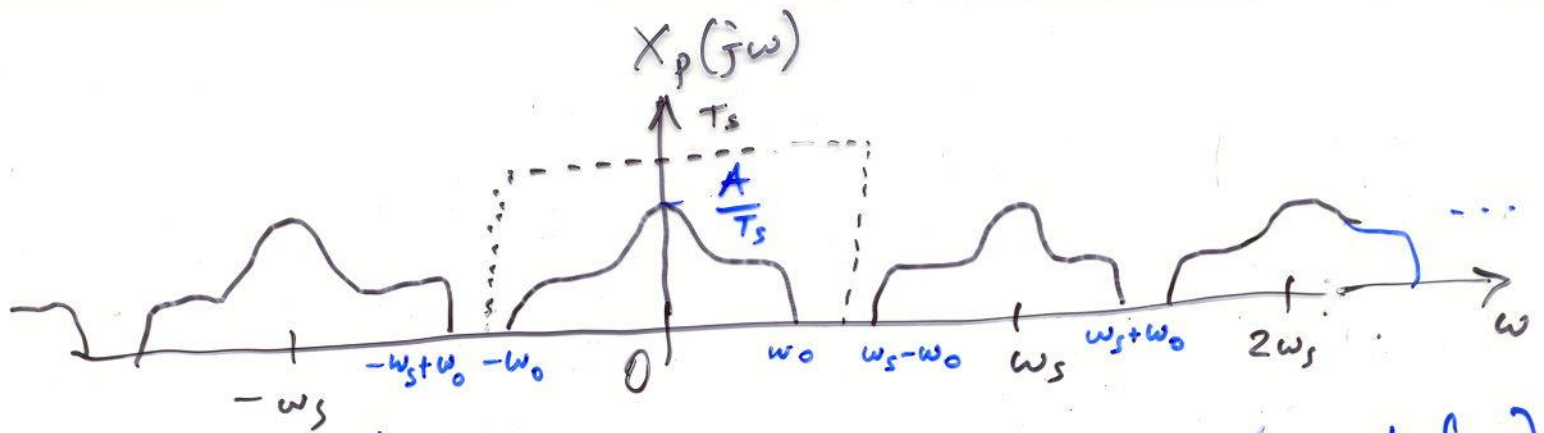
where $P(j\omega) = \frac{2\pi}{T_s} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi}{T_s} k) = \mathcal{F}\{p(t)\}$

$\omega_s = \frac{2\pi}{T_s}$



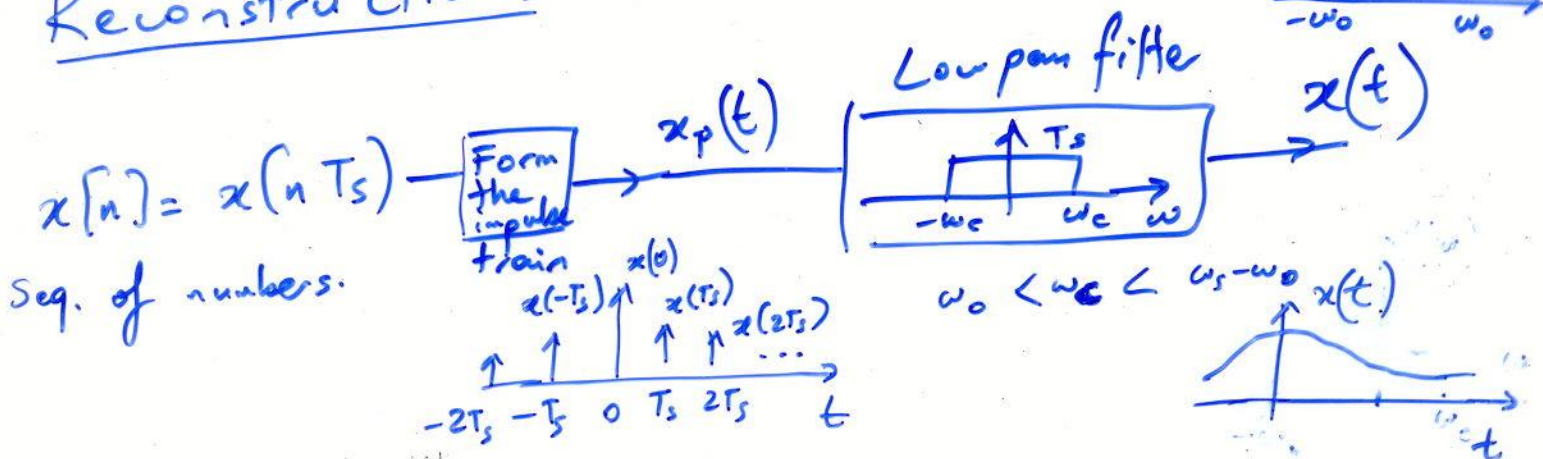
Since $X(j\omega) * \delta(\omega - k\omega_s) = X(j(\omega - k\omega_s))$

$$X_p(j\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j(\omega - k\omega_s))$$

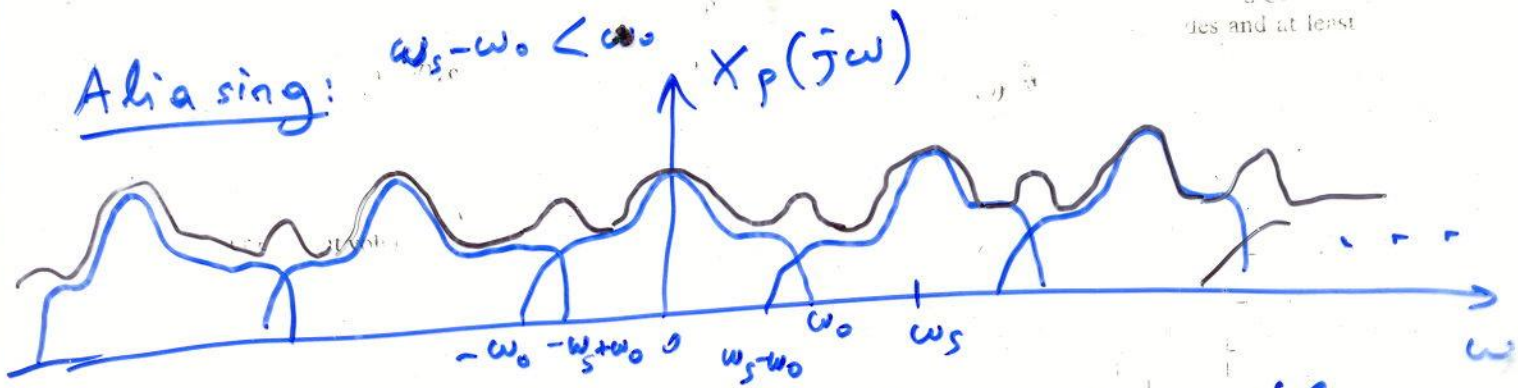


with the assumption $\omega_s - \omega_0 > \omega_0 \Rightarrow \omega_s > 2\omega_0$ (Nyquist freq.)

Reconstruction:



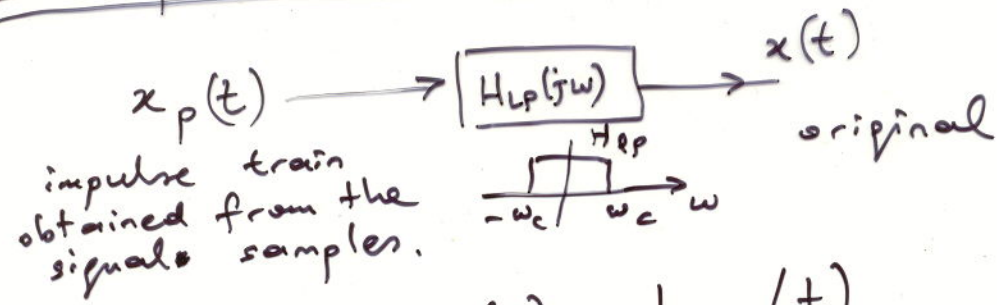
Aliasing: $\omega_s - \omega_0 < \omega_0$



There is overlap and it is impossible to reconstruct $x(t)$ from $x_p(t)$ or equivalently from the samples $x[n] = x(nT_s)$, $n=0, \pm 1, \pm 2, \dots$.

* Time domain example: stage-coach in Cowboy movies.

Interpolation Formula:



$$x(t) = x_p(t) * h_{LP}(t)$$

where $h_{LP}(t) = T \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c t}{\pi}\right)$

$$x_p(t) = \sum_{n=-\infty}^{\infty} x(nT) \delta(t - nT)$$

($\delta(t - t_0) * h(t) = h(t - t_0)$)

$$x(t) = \sum_{n=-\infty}^{\infty} x(nT) \underbrace{(h_{LP}(t) * \delta(t - nT))}_{h_{LP}(t - nT)}$$

$$x(t) = \sum_{n=-\infty}^{\infty} x(nT) T \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c(t - nT)}{\pi}\right)$$

where T : sampling period
 ω_c : cut-off freq. of the lowpass filter.
 (usually $\omega_c = \frac{\omega_s}{2} = \frac{2\pi}{T} \cdot 2 = \frac{\pi}{T}$)

RHS: $x(0), x(T), x(2T), \dots$

LHS: $x(t)$ cont. - time signal
 value at an arbitrary $t = t_0$:

The signal value at an arbitrary $t = t_0$:

$$x(t_0) = \sum_{n=-\infty}^{\infty} x(nT) \text{sinc}\left(\frac{\omega_c(t_0 - nT)}{\pi}\right), \quad \omega_c = \frac{\omega_s}{2}$$

Nyquist Frequency:
 $\omega_s > 2\omega_M$

Ex 11

$$y[n] = \frac{1}{4} x[n+1] + \frac{1}{2} x[n] + \frac{1}{4} x[n-1]$$

has an anticausal impulse response:

$$h[n] = \left\{ \frac{1}{4}, \frac{1}{2}, \frac{1}{4} \right\}$$

↑
n=0

In an FIR filter, filter coefficients determine the impulse response.

Ex 12

$$y[n] = \text{median} \{ x[n+1], x[n], x[n-1] \}$$

is a nonlinear system.