

CHP 9 LAPLACE TRANSFORMS

Definition 2

$$F(s) = \int_0^{\infty} f(t) e^{-st} dt = \mathcal{L}\{f(t)\}$$

- existence. $f(t)$ is piecewise continuous, $|f(t)| \leq K e^{at}$ (for some K)
 $\Rightarrow$ If integral converges for one s , we say that $F(s)$ exists.
- lower limit 0^- , to capture impulse at $t=0$ or discontinuity at $t=0$, in case $f(t)$ is not continuous at $t=0$. If $f(t)$ is continuous, it is not important.

$$\rightarrow u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$



$$F(s) = \frac{1}{s}$$

$$F(s) = \int_0^{\infty} e^{-st} dt = -\frac{e^{-st}}{s} \Big|_0^{\infty} = \frac{1}{s} \quad \text{for } \operatorname{Re}(s) > 0.$$

$$\rightarrow f(t) = e^{-\alpha t}$$

$\Rightarrow$

$$F(s) = \int_0^{\infty} e^{-st} \cdot e^{-\alpha t} dt = -\frac{e^{-(s+\alpha)t}}{s+\alpha} \Big|_0^{\infty} = \frac{1}{s+\alpha}$$

ALL TIME FUNCTIONS ARE DEFINED FOR $t \geq 0$!

BASIC PROPERTIES:

1) Uniqueness:

$$x(t) \leftrightarrow X(s)$$

$$\Rightarrow y(t) \leftrightarrow Y(s)$$

$$X(s) = \mathcal{L}\{x(t)\}$$

$$Y(s) = \mathcal{L}\{y(t)\}$$

$$x(t) = y(t) \quad \Leftrightarrow \quad X(s) = Y(s)$$

2) Linearity:

$$\alpha x(t) + \beta y(t) \Leftrightarrow \int_0^{\infty} [\alpha x(t) + \beta y(t)] e^{-st} dt = \alpha \int_0^{\infty} x(t) e^{-st} dt + \beta \int_0^{\infty} y(t) e^{-st} dt$$

$$= \alpha X(s) + \beta Y(s)$$

(α may be real or complex)

$$e^{j\omega t} \leftrightarrow \frac{1}{s-j\omega}, \quad e^{-j\omega t} \leftrightarrow \frac{1}{s+j\omega}$$

$$\cos \omega t = \frac{e^{j\omega t} + e^{-j\omega t}}{2} \leftrightarrow \frac{1}{2} \cdot \frac{1}{s-j\omega} + \frac{1}{2} \cdot \frac{1}{s+j\omega} = \frac{s}{s^2 + \omega^2}$$

$$\sin \omega t = \frac{e^{j\omega t} - e^{-j\omega t}}{2j} \leftrightarrow \frac{1}{2j} \cdot \frac{1}{s-j\omega} - \frac{1}{2j} \cdot \frac{1}{s+j\omega} = \frac{\omega}{s^2 + \omega^2}$$

1) Differentiation Rule.

$$f(t) \leftrightarrow F(s)$$

$$\text{what is } \mathcal{L}\left\{\frac{df}{dt}\right\} = ?$$

$$\boxed{\mathcal{L}\left\{\frac{df}{dt}\right\} = sF(s) - f(0)}$$

$$\Downarrow$$

$$\mathcal{L}\left\{\frac{d^2f}{dt^2}\right\} = s \mathcal{L}\left\{\frac{df}{dt}\right\} - f'(0) = s(sF(s) - f(0)) - f'(0)$$

$$= s^2 F(s) - sf(0) - f'(0)$$

$$\Downarrow$$

$$\boxed{\mathcal{L}\left\{\frac{d^nf}{dt^n}\right\} = s^n F(s) - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0)}$$

USEFUL IN SOLVING DIFFERENTIAL EQUATIONS

2) Integration Rule.

$$f(t) \leftrightarrow F(s)$$

$$\text{what is } \int_0^t f(\tau) d\tau \quad X(s) = ?$$

$$\mathcal{L}\left\{\int_0^t f(\tau) d\tau\right\} = \frac{1}{s} F(s)$$

$$r(t) = t \quad \Rightarrow \quad = \int_0^t 1 d\tau = \int_0^t u(\tau) d\tau$$

$$\therefore \mathcal{L}\{t u(t)\} = \frac{1}{s} \mathcal{L}\{u(t)\} = \frac{1}{s^2}$$

$$\therefore t^2 = 2 \int_0^t \tau d\tau \Rightarrow \mathcal{L}\{t^2 u(t)\} = \frac{2}{s} \cdot \frac{1}{s^2} = \frac{2}{s^3}$$

$$\Rightarrow \mathcal{L}\{t^n u(t)\} = \frac{n!}{s^{n+1}}$$

s-domain translation:

$$\mathcal{L}\{f(t)\} = F(s) \Leftrightarrow \mathcal{L}\{e^{-\alpha t} f(t)\} = \underline{\underline{F(s+\alpha)}}$$

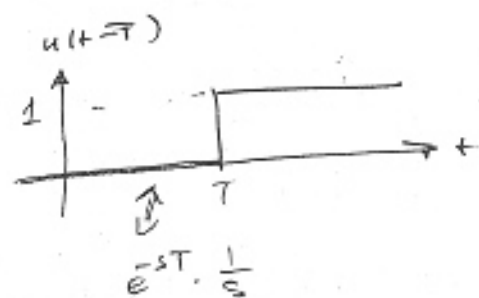
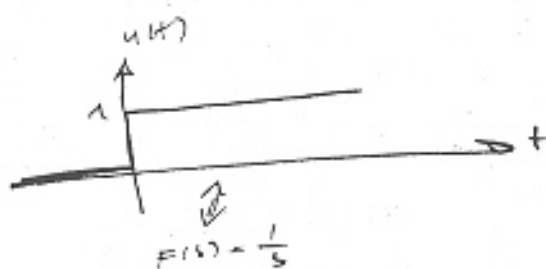
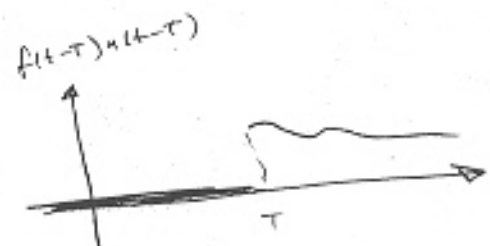
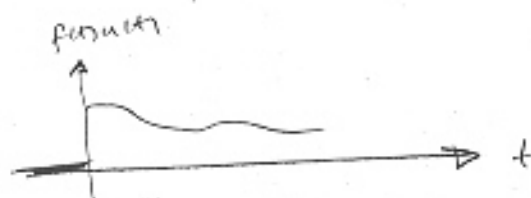
$$\mathcal{L}\{t u(t)\} = \frac{1}{s^2} \Leftrightarrow \mathcal{L}\{t e^{-\alpha t}\} = \frac{1}{(s+\alpha)^2}$$

$$\mathcal{L}\{\cos \beta t u(t)\} = \frac{s}{s^2 + \beta^2} \Leftrightarrow \mathcal{L}\{e^{-\alpha t} \cos \beta t u(t)\} = \frac{s+\alpha}{(s+\alpha)^2 + \beta^2}$$

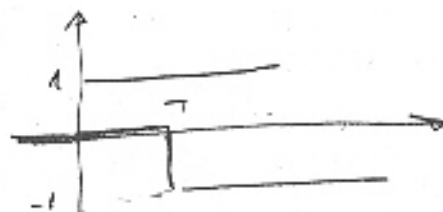
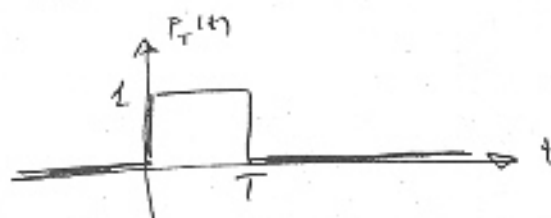
$$\mathcal{L}\{\sin \beta t u(t)\} = \frac{\beta}{s^2 + \beta^2} \Leftrightarrow \mathcal{L}\{e^{-\alpha t} \sin \beta t u(t)\} = \frac{\beta}{(s+\alpha)^2 + \beta^2}$$

time-domain translation:

$$\mathcal{L}\{f(t) u(t)\} = F(s) \Leftrightarrow \mathcal{L}\{f(t-T) u(t-T)\} = e^{-sT} F(s)!$$



PULSE:



$$P_T(t) = u(t) - u(t-T)$$

$$\mathcal{L}\{P_T(t)\} = \frac{1}{s} - e^{-sT} \frac{1}{s} = \frac{1 - e^{-sT}}{s}$$

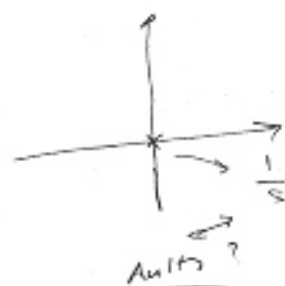
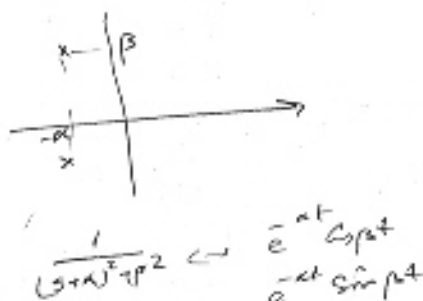
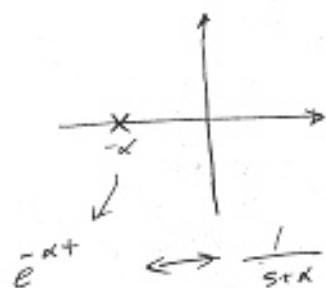
$$f(t) = (\bar{e}^{-2t} + 4t - 1) u(t).$$

$$F(s) = \frac{1}{s+2} + \frac{4}{s^2} - \frac{1}{s} = \frac{s^2 + 4s + 8 - s^2 - 2s}{s^2(s+2)} = \frac{2(s+4)}{s^2(s+2)}$$

- POLES - ZEROS :

$$F(s) = \frac{b_m s^m + b_{m-1} s^{m-1} + \dots + b_1 s + b_0}{a_n s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0} = K \cdot \frac{(s-z_1)(s-z_2)\dots(s-z_m)}{(s-p_1)(s-p_2)\dots(s-p_n)}$$

← zeros
→ poles



- INVERSE TRANSFORMATION (PARTIAL FRACTION EXPANSION)

$$F(s) = \frac{p(s)}{q(s)} = \frac{p(s)}{(s-p_1)(s-p_2)\dots(s-p_n)}$$

Assume proper rational function : $\deg(p) < \deg(q)$ [n > m]

* SIMPLE POLES : (no repeated poles)

$$F(s) = \frac{k_1}{s-p_1} + \frac{k_2}{s-p_2} + \dots + \frac{k_n}{s-p_n}$$

$$f(t) = k_1 e^{p_1 t} + k_2 e^{p_2 t} + \dots + k_n e^{p_n t}$$

$$k_i = (s-p_i) F(s) \Big|_{s=p_i} \quad \dots \quad k_i = (s-p_i) F(s) \Big|_{s=p_i}$$

$i=1, 2, \dots, n$

Example:

$$F(s) = 2 \cdot \frac{s+3}{s(s+1)(s+2)} = \frac{k_1}{s} + \frac{k_2}{s+1} + \frac{k_3}{s+2}$$

$$k_1 = s F(s) \Big|_{s=0} = 2 \cdot \frac{s+3}{\cancel{s}(s+1)(s+2)} \Big|_{s=0} = 2 \cdot \frac{3}{1 \cdot 2} = 3$$

$$k_2 = (s+1) F(s) \Big|_{s=-1} = \cancel{(s+1)} 2 \cdot \frac{s+3}{s \cancel{(s+1)}(s+2)} \Big|_{s=-1} = 2 \cdot \frac{1}{-2 \cdot (-1)} = 1$$

$$k_3 = (s+2) F(s) \Big|_{s=-2} = \cancel{(s+2)} 2 \cdot \frac{s+3}{s \cancel{(s+2)}(s+1)} \Big|_{s=-2} = 2 \cdot \frac{2}{(-1) \cdot (-1)} = -4$$

$$f(t) = \left(3 - 4e^{-t} + e^{-2t} \right) u(t)$$

COMPLEX ROOTS:

$$= \dots + \frac{k_1}{s - (-\alpha + j\beta)} + \frac{k_2}{s - (-\alpha - j\beta)} + \dots$$

$$k_2 = k_1^*$$

$$k_1 = |k| e^{j\theta}$$

$$k_2 = |k| e^{-j\theta}$$

$$f(t) = \dots |k| e^{j\theta} e^{(-\alpha + j\beta)t} + |k| e^{-j\theta} e^{(-\alpha - j\beta)t}$$

$$= \dots + |k| e^{-\alpha t} e^{j(\beta t + \theta)} + |k| e^{-\alpha t} e^{-j(\beta t + \theta)} + \dots$$

$$= \dots + 2|k| e^{-\alpha t} \cos(\beta t + \theta) + \dots$$

Example: (p. 451)

$$F(s) = \frac{20(s+3)}{(s+1)(s^2+2s+5)} = \frac{k_1}{s+1} + \frac{k}{s - (-1+j2)} + \frac{k^*}{s - (-1-j2)}$$

$$s^2+2s+5=0 \Rightarrow \begin{aligned} s_1 &= -1+j2 \\ s_2 &= -1-j2 \end{aligned}$$

$$k_1 = (s+1) F(s) \Big|_{s=-1} = 20 \cdot \frac{s+3}{s^2+2s+5} \Big|_{s=-1} = 20 \cdot \frac{2}{1-2+5} = 10$$

$$k = \left. (s - (-1+j2)) F(s) \right|_{s=-1+j2} = 20 \frac{s+3}{(s+1)(s-(-1-j2))} \bigg|_{s=-1+j2} = 20 \cdot \frac{-1+j2+3}{j2 \cdot j4}$$

$$= 20 \cdot \frac{2(1+j)}{-8} = -5(1+j) = 5\sqrt{2} e^{j\frac{5\pi}{4}}$$



$$f(t) = \left[10e^{-t} + 10\sqrt{2} \cos\left(2t + \frac{5\pi}{4}\right) \right] u(t).$$

MULTIPLE POLES:

$$F(s) = \frac{n(s)}{(s-p_1)^m \dots} = \frac{k_{11}}{(s-p_1)^m} + \frac{k_{12}}{(s-p_1)^{m-1}} + \dots + \frac{k_{1m}}{s-p_1}$$

$$(s-p_1)^m F(s) = k_{11} + k_{12}(s-p_1) + \dots + k_{1m}(s-p_1)^{m-1} + \dots$$

$$k_{11} = \left. (s-p_1)^m F(s) \right|_{s=p_1}$$

$$k_{12} = \left. \left\{ \frac{d}{ds} (s-p_1)^m F(s) \right\} \right|_{s=p_1} \dots k_{1m} = \frac{1}{(m-1)!} \left. \left\{ \frac{d^{m-1}}{ds^{m-1}} (s-p_1)^m F(s) \right\} \right|_{s=p_1}$$

$$k_{13} = \frac{1}{2} \left. \left\{ \frac{d^2}{ds^2} (s-p_1)^m F(s) \right\} \right|_{s=p_1}$$

How to find the inverse transform?

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}, \quad \mathcal{L}\{t^n e^{pt}\} = \frac{n!}{(s-p)^{n+1}} \Rightarrow \mathcal{L}\{t^{n-1} e^{pt}\} = \frac{(n-1)!}{(s-p)^n}$$

$$\Rightarrow \boxed{\mathcal{L}^{-1}\left\{\frac{k}{(s-p)^n}\right\} = \frac{k}{(n-1)!} e^{pt} t^{n-1}}$$

$$f(t) = k_{1m} e^{p_1 t} + \dots + \frac{k_{12}}{(m-2)!} e^{pt} t^{m-2} + \frac{k_{11}}{(m-1)!} e^{pt} t^{m-1} + \dots$$

$$F(s) = \frac{4(s+3)}{s(s+2)^2} = \frac{k_2}{s} + \frac{k_{21}}{(s+2)^2} + \frac{k_{22}}{(s+2)}$$

$$k_2 = sF(s) \Big|_{s=0} = \frac{4(s+3)}{(s+2)^2} \Big|_{s=0} = \frac{4 \cdot 3}{4} = 3$$

$$k_{11} = (s+2)^2 F(s) \Big|_{s=-2} = \frac{4(s+3)}{s} \Big|_{s=-2} = \frac{4 \cdot 1}{-2} = -2$$

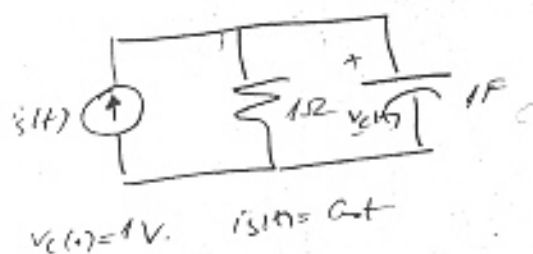
$$k_{12} = \frac{1}{ds} \left\{ \frac{4(s+3)}{s} \right\} \Big|_{s=-2} = \frac{4s - (4s+12)}{s^2} \Big|_{s=-2} = \frac{-12}{s^2} \Big|_{s=-2} = -3$$

$$F(s) = \frac{3}{s} - \frac{2}{(s+2)^2} - \frac{3}{s+2}$$

$$f(t) = (3 - 3e^{-2t} - 2te^{-2t})u(t)$$

$$\mathcal{L}^{-1} \left\{ \frac{1}{(s+2)^2} \right\} = \frac{1}{1!} e^{-2t} \cdot t$$

EXAMPLE:



$$I_s = \frac{V_c}{1} + C \cdot \dot{V}_c$$

$$\frac{I_s}{s} = \frac{V_c(s)}{(s+1)} + sV_c(s) - v_c(0^-)$$

$$\Rightarrow V_c(s) = \left[\frac{3}{s^2+1} + 1 \right] \frac{1}{s+1} = \frac{s^2+s+1}{(s+1)(s^2+1)} = \frac{k_1}{s+1} + \frac{k}{s-j} + \frac{k^*}{s+j}$$

$$k_1 = (s+1)V_c(s) \Big|_{s=-1} = \frac{3s^2+s+1}{s^2+1} \Big|_{s=-1} = \frac{1}{2}$$

$$k = (s-j)V_c(s) \Big|_{s=j} = \frac{s^2+s+1}{(s+1)(s+j)} \Big|_{s=j} = \frac{-1-j+1}{(1+j)2j} = \frac{1}{2} \cdot \frac{1}{j2} e^{j45^\circ} = \frac{1}{2\sqrt{2}} e^{j45^\circ}$$

$$v_c(t) = \frac{1}{2} e^{-t} + \frac{1}{\sqrt{2}} \cos(t-45^\circ)$$

If we used phasors $\Rightarrow I_s = V_c + j \cdot 1 \cdot V_c = (1+j)V_c = 1$ $V_c = \frac{1}{\sqrt{2}} e^{j45^\circ}$

$$v_c(t) = \text{Re} \left\{ \frac{1}{\sqrt{2}} e^{-jt} \cdot e^{j45^\circ} \right\} = \frac{1}{\sqrt{2}} \cos(t-45^\circ)$$