EEE 391: Basics of Signals and Systems Fall 2024–2025 Analytical Assignment 2

1. The frequency response of a linear time-invariant filter is given by the formula:

$$H(e^{j\hat{\omega}}) = (1 - e^{-j\hat{\omega}})(1 - e^{j\pi/3}e^{-j\hat{\omega}})(1 - e^{-j\pi/3}e^{-j\hat{\omega}})$$

- (a) Write the difference equation that gives the relation between the input x[n] and the output y[n].
- (b) What is the output if the input is $x[n] = \delta[n]$?
- (c) If the input is of the form $x[n] = Ae^{j\phi}e^{j\hat{\omega}n}$, for what values of $-\pi \leq \hat{\omega} \leq \pi$ will y[n] = 0 for all n?
- 2. Consider an FIR filter with coefficients $b_k = \{2, 0, 5, 0, 2\}$.
 - (a) If the input signal is $x[n] = \delta[n] \delta[n-2]$, make a plot of the output y[n]. Include zero values on the plot.
 - (b) Determine the frequency response, $H(e^{j\omega})$
 - (c) Determine and plot the magnitude and the phase of $H(e^{j\omega})$
- 3. Suppose that a LTI system has a z-transform system function equal to:

$$H(z) = 7 - 6z^{-1} - 5z^{-3} + 4z^{-4}$$

- (a) Determine the difference equation that relates the output y[n] of the system to the input x[n].
- (b) Determine and plot the impulse response h[n].
- (c) Determine the step response, i.e., the output when the input is:

$$u[n] = \begin{cases} 1, & n \ge 0\\ 0, & n < 0 \end{cases}$$

4. A linear time-invariant system is described by the difference equation:

$$y[n] = x[n] + x[n-4]$$

- (a) Find its impulse response h[n].
- (b) Find its system function H(z).
- (c) Plot the poles and zeros of H(z) in the z-plane. (Recall that $-1 = e^{j\pi k}$ where k is an odd integer.)
- (d) Find the frequency response $H(e^{j\omega})$ and express it in polar form (magnitude and phase).
- (e) Carefully sketch and label a plot of $|H(e^{j\omega})|$ for $-\pi < \omega < \pi$.

5. Answer the following questions about the system whose z-transform system function is:

$$H(z) = \frac{1 + 0.8z^{-1}}{1 - 0.9z^{-1}}$$

- (a) Determine the poles and zeros of H(z).
- (b) Determine the difference equation relating the input and output of this filter.
- (c) Derive a simple expression (purely real) for the magnitude-squared of the frequency response $|H(e^{j\hat{\omega}})|^2$.
- (d) Is this filter a Lowpass or Highpass filter? Explain your answer.
- 6. You are given the following two signals:

$$x_1(t) = \begin{cases} t+3, & \text{for } t \in [-3,0], \\ -t+3, & \text{for } t \in [0,3], \\ 0, & \text{otherwise,} \end{cases}$$

$$x_2(t) = \begin{cases} 1, & \text{for } t \in [-3,3], \\ 0, & \text{otherwise.} \end{cases}$$

- (a) Sketch $x_1(t)$ and $x_2(t)$ over the interval $-3 \le t \le 3$.
- (b) Calculate $x_1(t) * x_2(t)$, $x_1(t) * x_1(t)$, and $x_2(t) * x_2(t-3)$.
- 7. Consider the following continuous-time LTI system:

Diagram:

$$x(t) \longrightarrow H_1(j\omega) \longrightarrow H_2(j\omega) \longrightarrow y(t)$$

where

$$H_1(j\omega) = \frac{1}{j\omega+1}$$
 and $H_2(j\omega) = \frac{1}{j\omega+2}$

- (a) Determine the differential equation describing the overall system.
- (b) Find the impulse response of this system from the frequency response.
- (c) Find the output y(t) when x(t) is a signal with the Fourier Transform $X(j\omega) = j\omega$. Use the frequency response.

8. Consider the following *high-pass filter* whose frequency response is given below:

$$H(j\omega) = 1 - \operatorname{rect}\left(\frac{\omega}{4\pi}\right)$$

Recall that the rect function is defined as:

$$\operatorname{rect}(\theta) = \begin{cases} 1, & \text{if } -\frac{1}{2} < \theta < \frac{1}{2}, \\ 0, & \text{otherwise.} \end{cases}$$

(a) The following signal is the input signal of this system:

$$x(t) = \frac{\sin(4\pi t)}{\pi t} \cos(2\pi t).$$

- i. Let $X(j\omega)$ be the Fourier transform of the input signal x(t). Sketch and clearly label $X(j\omega)$.
- ii. Let $Y(j\omega)$ be the Fourier transform of the output signal y(t). Sketch and clearly label $Y(j\omega)$.
- (b) The output signal y(t) is processed to obtain a new signal:

$$z(t) = \frac{\sin(2\pi t)}{\pi t} y(t).$$

- i. Let $Z(j\omega)$ be the Fourier transform of z(t). Sketch and clearly label $Z(j\omega)$.
- ii. Find the time-domain expression for y(t).